

YSC-8361

AC Servo System

Instruction manual

IMPORTANT READ CAREFULLY BEFORE USE KEEP FOR FUTURE REFERENCE

YSC-8361 controller is used for an industrial sewing machine. With industrial sewing machine, it is normal to carry out work while positioned directly in front of moving parts such as the needle and thread take-up, and consequently there is always a danger of injury that can be caused by these parts. So when you ready to operate the machine, please follow the instructions from trained personnel and instructors regarding safe and correct operation.

1. NOTICE

1.1 Work environment

- \blacktriangle Please use 220V AC in ±10% ranges.
- ▲ To avoid the false operate, please keep the product away from the high electromagnetic interference.
- ightharpoonup Please operate in the area which temperature is 5 °C ~45 °C and humidity is 80% or less.

1.2 Notice of installation

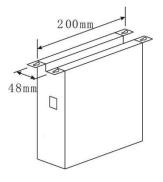
- ▲ Turn off the power and unplug the cord before installation.
- ▲ The wire must not set to be near the wheel and other movable parts.
- ▲ To avoid the static interference and current leakage, all grounding must be done.

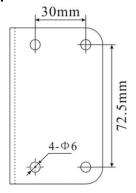
1.3 Notice of safety

- ▲ Turn off the power before maintenance and repairs or raising the machine arms, or changing needle, or threading needle.
- ▲ Please don't open the box except the professional.
- ▲ When turn on the machine in the first time, use low speed to operate and check the correct rotation direction.
- ▲ During machine operation, don't touch any moving parts.
- All moving parts must use the protective device to avoid the body contact and objects insertion.
- ▲ When there is water or other liquid, or caustic material on box or motor, you must stop operation and turn off the power.
- ▲ All connector shouldn't be plug and unplug when power on.
- ▲ The connector should be plug and unplug in the correct method.

2. INSTALLATION AND ADJUSTMENT

2.1 Dimension of control box and speed controller bracket(direct driven)



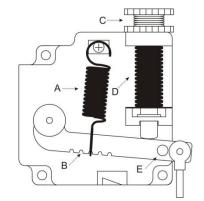


Control box

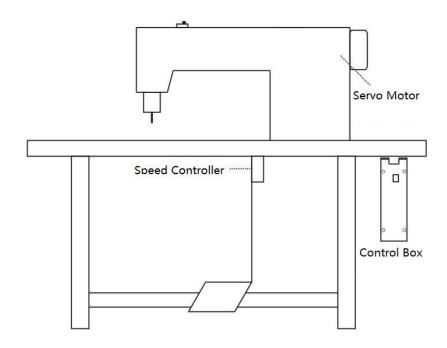
Speed controller bracket

2.2 Speed controller

- A: Forward spring
- B: Groove
- C: Bolt group
- D: Back spring
- E: Pothook hole



2.3 Installation diagram of system



3. ELECTRICAL CONNECTION

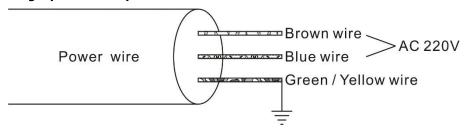
3.1 Connecting the power supply

Work on the electrical equipment may only be performed by qualified technicians or personal who have undergone the necessary training.

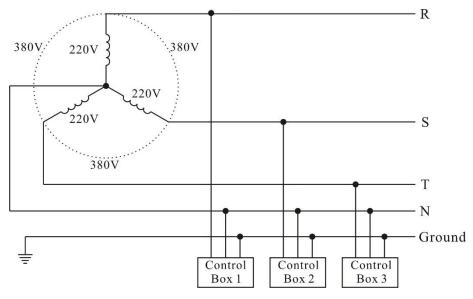
Always pull the power plug before working on the electrical equipment.

Connect the control to a grounded AC voltage, the rated voltage is in the range of 220V + 10%

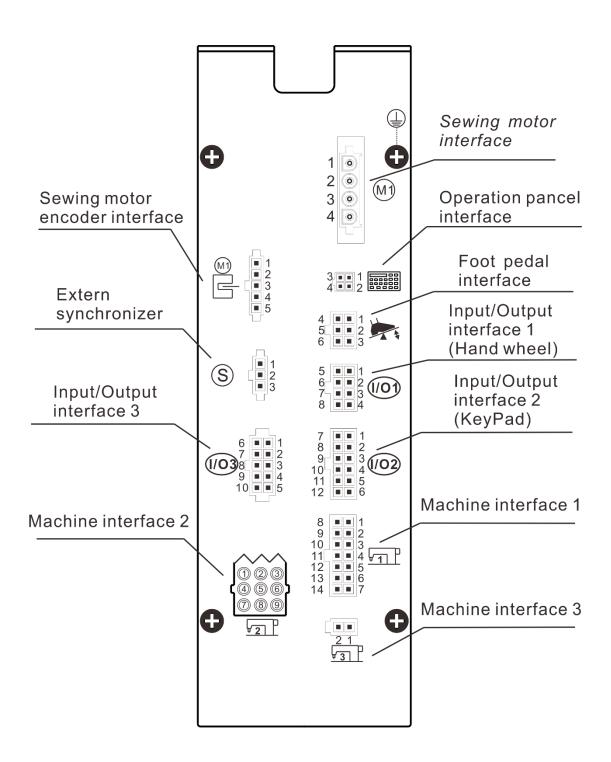
3.2 Single phase 220V power connection

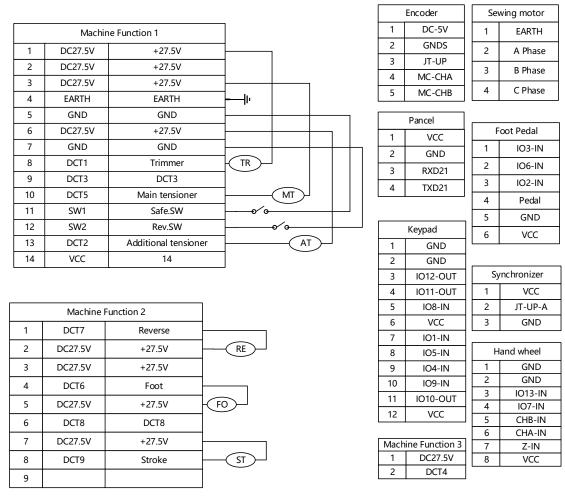


3.3 Three phase 380V power connection



4. CONNECTOR DIAGRAM

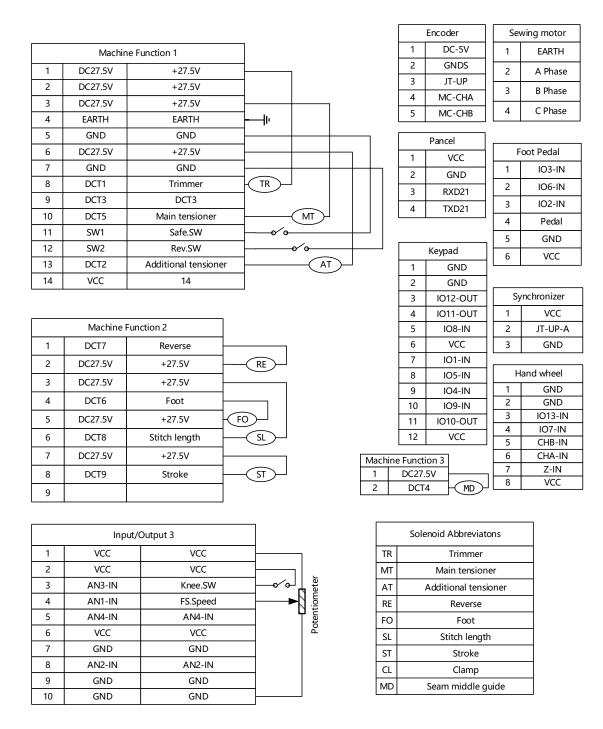




	Input/0	Output 3	
1	VCC	VCC	
2	VCC	VCC	
3	AN3-IN	Knee.SW	
4	AN1-IN	FS.Speed.SW1	o′o-
5	AN4-IN	AN4-IN	
6	VCC	VCC	
7	GND	GND	
8	AN2-IN	FS.Speed.SW2	• ⁄•
9	GND	GND	
10	GND	GND	

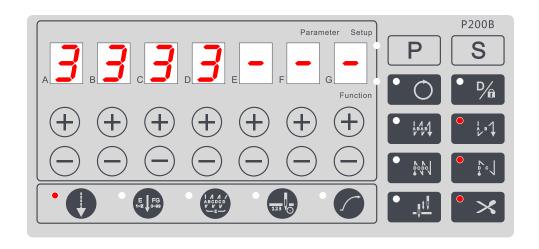
Solenoid Abbreviatons		
TR	Trimmer	
MT	Main tensioner	
АТ	Additional tensioner	
RE	Reverse	
FO	Foot	
SL	Stitch length	
ST	Stroke	
CL	Clamp	
MD	Seam middle guide	

20665 series



898 series

5. OPERATING FIELD P200B



	1	
	• !.1	Single start tacking, A is the stitches of forth
	```	sewing; B is the stitches of back sewing. They are both in range 1~15
Start backtack		Double start tacking, A is the stitches of forth
	• 144	sewing; B is the stitches of back sewing. They are
	V V ↓	hoth in range 1, 15
		both in range 1~15。
		Single end tacking, C is the stitches of back
		sewing; D is the stitches of forth sewing. They
End backtack		are both in range 1~15
	• ۸۸۱	Double end tacking, C is the stitches of back
	penc	sewing; D is the stitches of forth sewing. They
		are both in range 1~15
		▲ As the pedal is stepped forward, the starttacking(if selected) will be done automatically, then machine will
		start normal sewing. Once the pedal returned to
Free Sewing		balance, machine will stop immediately.
Tree sewing		▲ As the pedal stepped backward, the end
		tacking, trimming and wiping (if selected) will be
		done automatically
		▲ Once the pedal is stepped forward, F, G stitches will
Constant-Stitch		be completed with E times.
Sewing	E 1-Z 0-99	▲ Constant-Stitch Sewing will perform the number of
Sewing		segments and times as setting, when the stitches are
		zero, machine will stop immediately.
		▲ Once the pedal is stepped forward, all the seams of
Bar-Tacking	A A A A A A A A A A A A A A A A A A A	bar tacking, A, B, C, D sections will be completed with
Sewing		E times, and the trimming will be done automatically.
_		▲ The pedal must be returned to balance for next
Lower thread		sewing.
Lower thread Counter	123	Enter lower thread counter interface
Counter		

Soft start		Enable or disable the soft start
Needle Up / Needle Down	• _\!\!\!	Select the stop position of needle bar
Trimming Enable	• ×	Enable or disable the trimming
Interface Selection		Switch current interface to another
One-Key Default /Lock keys	• D/n	<ul><li>▲ Sewing interface: lock the keypad</li><li>▲ Parameter interface: restore a parameter to default</li></ul>
Parameter Function	Р	Enter or exit parameter function interface
Save	S	Confirm and save current value of parameter
Add	0	Value increase
Sub		Value decrease

# 6. GET STARTED WITH YOUR MACHINE

Before operating the controller, the following items must be inspected and set up to ensure safe and reliable operation:

# 6.1 Machine ID

# 6.1.1 How to change the machine ID

Press hold  $\|A+\|$  key and turn on the power to access to adjust the machine ID, seven-segment displays F,G will display the ID, change it

and press S to save.

#### 6.1.2 Table of machine ID

ID	Model	Unit(sti/min)
1	GC20665KL14D3T3	2500
2	GC20665L14D3T4	2500
3	GC20666L14D2T4	2200
4	TW1-898L14D2T5	3500
5	TW1-999L14D2T5	2800
6	TW1-999L14D3T5-001	2800
7	TW1-899SL14D2T5	2800
8	TW2-898L14D2T5	2800
9	TW2-999L14D2T5	2500
10	GC24676BD2T5	2500
11	GC20676L14D2T3	2200
12	GC2263-1D3T3	2500
13	TW1-899L14D2T4	2800

# 6.2 Adjust the ZERO OF THE MACHINE

- Press and switch on the power, the panel displays "ZERO"
- Turn hand wheel slowly, the panel displays the current degree.
- When the needlebar is at the highest position, press save
- Restart the control box

#### 7. OPERATING ELEMENTS

#### 7.1 Single start back-tacking setting

- $\blacksquare$  A Stitches = 0
  - Seven-segment display A display [-]. Sewing process: B stitches back normal sewing.
- A Stitches  $\neq$  0

Sewing process: A stitches forth – B stitches back – normal sewing

# 7.2 Double start back-tacking setting

- $\blacksquare$  A Stitches = 0
  - Sewing process: B stitches back B stitches forth B stitches back normal sewing.
- A Stitches  $\neq$  0

Sewing process: A stitches forth – B stitches back – A stitches forth – B stitches back – normal sewing

# 7.3 Single end back-tacking setting

- D Stitches = 0
  - Seven-segment display D display  $\llbracket \rrbracket$ .
  - Sewing process: C stitches back end.
- D Stitches ≠ 0

Sewing process: C stitches back – D stitches forth – end.

#### 7.4 Double end back-tacking setting

- D Stitches = 0
  - Sewing process: C stitches back C stitches forth C stitches back end.
- D Stitches ≠ 0

Sewing process: C stitches back – D stitches forth – C stitches back – D stitches forth – end.

#### 7.5 Lower thread counter

Set A11 to "1" to active the counter.

- Initialize the counter: Press , the initial value of the lower thread counter which was set previously will be shown. Adjust it to a suitable value.
- How the counter works:

- Display initial value
- The counter reduces by 1 for every 10 stitches sewn.
- If the counter less than 1, the display area twinkled and buzzer sounds for 3 times. The machine will not start up again. Press the warning will disappear and sewing will be possible, the counter reduces continue.
- Press S again, the display will return to the initial value

#### 7.6 Product quantity counter

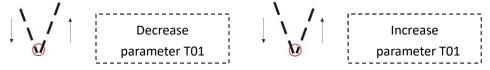
Set A11 to "1" to active the counter.

- Enter interface: Special function interface SN F2, refer to 6.2
- **Data acquisition:** In SN F2 interface, press S will be into collect process interface, seven-segment display D displays 「L』, seven-segment displays E,F,G will display the number of stitches for this process. It records the number of stitches and the number of trimmer. Press S to save the data and return SN F2 interface.
- How the Counter works: If sewn the number stitches more than the number of stitches collected 90%, and the number of trimming times more than collected, the counter add 1.
- Clear Counter: press

#### 7.7 Adjust the backtack

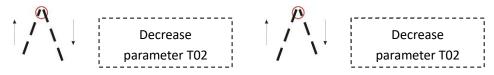
Adjusting of RVE.SOL action time

For start/end backtack or bar tacking, if unbalanced situation is appeared during natural direction to reverse direction, please correct it as below:



■ Adjusting of RVE.SOL release time

For start/end tacking or bar tacking, if unbalanced situation is appeared during reverse direction to natural direction, please correct it as below:



#### 7.8 Quick functions on the keypad



Figure 1: Keypad on the machine arm

Foot stroke	<b>S</b>	Toggle foot stroke level
		This key cancels the general setting for
Start and end	10-1	sewing start and end strips. If strips are
strips	N1-0	activated, pressing the key disables the next
		strip. If no strips are activated pressing the
		key sews the next strip.
		If the key is selected the needle moves to a
Position of the	Ţ <u>I</u>	specific position. This position is determined
needle		individually via the parameter settings, more
		information read D15, D16
	•	If this key is selected, the machine sews using
Stitch Length		the smaller stitch length selected at lower
		adjusting wheel for the stitch length
Additional		This key switches on the additional thread
thread tension	7)(	tension
	$\otimes$	If the pause switch is triggered, all functions
Pause		are locked except parameters, the adjacent
		led light up, panel display "PAUSE"

# 7.9 Lock the hot keys and keypad



if key is triggered, all functions on the keypad and hot keys are invalid.

#### 7.10 Electronic hand wheel

Turning the hand wheel:

The value of "A23" is 1, electronic hand wheel is activated. By turning the hand wheel, you can move the needle bar forwards or backwards.

#### 7.11 Hot keys

Pressing the Reverse switch:

Default: Reverse.

Refer to Parameter list, A04.

Pressing the hand wheel:

Default: None

Refer to Parameter list, A05.

#### 7.12 Quick stroke adjustment via knee switch

On machines with quick stroke adjustment activated via a knee switch, the elevated sewing foot stroke is switched via the knee switch.

#### 8. OPERATION OF THE SPECIAL FUNCTION INTERFACE

Press could be access special function interface from normal function interface, showed as below:



Figure 2: Function Interface

Bar A and B according to SN of function, bar D~G display contents, press **B+** and **B-** to select function:

#### 8.1 Dynamic speed limitation

SN F1: display current speed up limitation, could be change during running.

### 8.2 Product quantity counter

SN F2: display the product quantity

#### 8.3 Machine degree

SN F3: display the machine degree.

# 8.4 Torque enhancement function at low speed

SN F4: display D: press **D+** and **D-** to open/close the function. Display F,G: 0~10, the gear.

#### 8.5 Actual speed display

SN F5: display the actual speed.

#### 8.6 Lower thread counter

SN F6: display how much the lower thread is remaining

#### 9. PARAMETER INSTRUCTION

### 9.1 Setting parameter

Press P to enter Parameter Interface.

Seven-Segment display E display the parameter type, press "E+" and "E-" key to change it.

Seven-Segment display F, G display the parameter index, press "F+", "F-", "G+", "G-" key to change it.

Seven-Segment displays A, B, C, D display the parameter value, press the keys under them to change it.

For example, Graph4: parameter index is 1, type is P, value of "S01" is 2000, the nixie tube will blink when change the value. Press S to confirm, press P to cancel and return to sewing interface.



Figure 3: Parameter Interface

#### 9.2 Get the permission of setting O type parameter

Only S, T and A type parameter can be select normally, if you want to change the O type parameter, you must power on while press P key, when you see 「DO EN」, you get the permission successfully.

#### 9.3 Parameter solidifying

If users want to change some parameter's default value, then select the parameter, press maintain a moment, after <code>SDOK</code> displaying, the default value has been changed.

# 9.4 Restore parameter through one-key default

Select any parameter in parameter interface, can be used to recall the default value. The bar will be twinkling if modified, use to confirm or repeal change

#### 9.5 Controller recovery

# Resume the default value of all parameters

Set parameter **O17** to "ON", turn on the power again, after twinkling of "INIT" finished, all parameters have been default value themselves

# Restore Factory Defaults

Set parameter **O51** to "ON", turn on the power again.

#### 9.6 Abate safety switch

If you want to abate the function of Safe SW., you can change the value of "O31" from "1" to "0" normally, in a particular case, for example, the Safe SW. broke down, you can power on while press "C+" key to abate the function of Safe SW.

warning: it means potential security problems for you if you abate the function of Safe SW., so attention please.

#### 9.7 General parameter table

SN	RANGE	DESCRIPTION
S type Parameter		
S01	500~3500spm	Maximum sewing speed
S02	150∼500spm	Minimum sewing speed
S03	500~2000spm	Speed adjustment for start back-tacking

500~2000spm	Speed adjustment for end back-tacking
500~2000spm	Speed adjustment for bar-Tacking
500~2000spm	Speed adjustment for constant-stitch sewing
150∼300spm	Speed adjustment for trimmer
200∼500spm	Soft start speed
500~3500spm	Speed adjustment for foot stroke gear 1
500~3500spm	Speed adjustment for foot stroke gear 2
500~3500spm	Speed adjustment for foot stroke gear 3
500~3500spm	Speed adjustment for foot stroke gear 4
500~3500spm	Speed adjustment for foot stroke gear 5
500~3500spm	Speed adjustment for foot stroke gear 6
500~3500spm	Speed adjustment for min-foot stroke
50~500spm	Speed adjustment for pull back after trim
rameter	•
1~200(millisecond)	Action time of the REV SOL.
1~200(millisecond)	Release time of the REV SOL.
1~500(millisecond)	Foot lifer-Delay time adjustment for pedal's feet lift
	position
1~500(millisecond)	Running delay time adjustment for Automatic Foot
	Lifer
1~1000(millisecond)	Safety switch-Delay time adjustment for machine
	vibration
1~200(millisecond)	Pedal-Delay time adjustment for pedal vibration
1~1000(millisecond)	Delay time adjustment when A20/A22 set as 1
rameter	
0~1	Needle positions
	1 = Up Position
	0 = Down Position
0~1	Automatic Constant-Stitch sewing
	1 = On
	0 = Off
0~1	Correction stop mode
	1 = stop position accord to D15, D16
	0 = random
0~13	Function selection of reverse switch
	0 = none
	1 = reverse
	2 = forward correction
	3 = backward correction
	4 = forward correction at machine stop, reverse at
	machine run
	5 = backward correction at machine stop, reverse at
	500~2000spm 500~2000spm 150~300spm 200~500spm 500~3500spm 500~3500spm 500~3500spm 500~3500spm 500~3500spm 500~3500spm 500~3500spm 10~500spm 10~500spm 10~500spm 10~500(millisecond) 10~500(millisecond) 10~500(millisecond) 10~1000(millisecond)

		6 = none
		7 = none
		8 = trim at normal sewing, foot lifer after trimming 9 = foot stroke
		10 = single backtack supression
		11 = 2 nd STITCH LENGTH
		12 = additional thread tension
		13 = thread mode
A05	0~13	Function selection of hand wheel switch, refer to A04
A06	0~1	Trim selection
		1 = trimmer valid
		0 = trimmer invalid
A07	0~1	Lock machine buttons selection (machine buttons
		includes Hot Keys, Hand Wheel Switch, Reverse
		Switch)
		0: machine buttons work
		1: machine buttons not work
A09	0~1	Foot lift selection
		1: Foot lifer function valid
		0: Foot lifer function invalid
A10	0~1	Clamp selection
		1: Clamp valid
		0: Clamp invalid
A11	0~1	Product Quantity Counter
		1 = On
		0 = Off
A12	0~1	Lower thread Counter
		1 = On
		0 = Off
A13	0~1	Pull Back after Trim (angle refer to O35)
		1 = On
		0 = Off
A14	0~1	Automatic Foot Lifer when stopped
		1 = ON
		0 – Off
A15	0~1	Automatic Foot Lifer after trimming
		1 = On
		0 = Off
A16	0~1	Automatic constant-stitch sewing after start
		backtacking (only when A02=0)
		1 = On
		0 = Off
A17	0~1	Automatic end backtacking for constant-stitch sewing
		(only when A02=0)
		(Offiny Which Au2—U)

		1 = On
		0 = Off
A18	0~1	Upper position when switch on the control
7110		1 = On
		0 = Off
A19	0~2	Function when Half-Heeling the pedal
AID	0.12	2: thread cutting
		1: foot lift
		0: Balance
A20	0~1	Mode of start back-tacking (only for free sewing)
AZU	0.11	1: stitch for stitch
		0: normal
A21	0~1	Soft start
A22	0~1	Mode of end back-tacking (only for free sewing)
AZZ	0.11	1: stitch for stitch
		0: normal
A23	0~1	Electronic handwheel
7123		1 = On
		0 = Off
A27	0~3	Mode of thread tension and thread tension reduction
,,,,,		when sewing foot lift is active
		0 = no thread tension lift
		1 = thread tension lift in the seam
		2 = thread tension lift after trimming
		3 = thread tension lift in the seam and after trimming
A28	0~1	Automatic open additional thread tension when foot
		stroke adjust
		0 = not related to Knee SW.; not related to Keypad;
		1 = related to Knee SW.; not related to Keypad;
		2 = not related to Knee SW.; related to Keypad;
		3 = related to Knee SW.; related to Keypad;
A30	0~1	Correction mode
		0: single correction
		1: continuously correction
A36	0~11	Quick function on the keyboard key1
		0: none
		1: foot stroke
		2: start and end strips
		3: forward correction
		4: stitch length
		5: additional thread tension
		6: pause
		7: add power when low speed
		8: reverse

		9: parting foot
		10: threading mode 11: backward correction
A37	0~11	
A3/	0~11	Quick function on the keyboard key2  Refer to A36
A 2.0	0~11	
A38	0~11	Quick function on the keyboard key3
420	0.11	Refer to A36
A39	0~11	Quick function on the keyboard key4
A 40	0.11	Refer to A36
A40	0~11	Quick function on the keyboard key5
		Refer to A36
A41	0~11	Quick function on the keyboard key6
		Refer to A36
A43	0~1	Electronic handwheel rotation and motor steering
		correspondence
		0: same
		1: opposite
A50	0~1	Start with 2 nd stitch length
A51	0~3	Mode for automatic raising of the seam middle guide
		0: Do not raise
		1: With sewing foot lift
		2: During bark-tacking and reverse
		3: During back-tacking and reverse and sewing foot lift
D type P	Parameter	
D01	0~359(°)	Angle of needle bar up lever
D02	0~359(°)	Angle of needle bar down lever
D03	0~359(°)	Switch-on angle of Trimmer
D04	0~359(°)	Switch-off angle of Trimmer
D05	0~359(°)	Switch-on angle of Reverse SOL.
D06	0~359(°)	Switch-off angle of Reverse SOL.
D07	0~359(°)	Switch-on angle of thread clamp
D08	0~359(°)	Switch-off angle of thread clamp
D13	0~359(°)	Switch-on angle of thread tension
D14	0~359(°)	Switch-off angle of thread tension
D15	0~359(°)	Correction angle 1
D16	0~359(°)	Correction angle 2
D17	0~359(°)	Switch-on angle of short thread trimmer
		(only for TW1-999L14D3T5-001)
D18	0~359(°)	Switch-off angle of short thread trimmer
		(only for TW1-999L14D3T5-001)
O type P	Parameter	
O01	1~10(stitch)	Number of soft start stitches
O04	1~1000(millisecond)	Delay time for stitch for stitch backtrack. Refer to A20
		,

1 = Automatic foot lifter release after the time of O07   0 = always hold	O06	0~1	Automatic foot lifter release				
007         S-30(second)         Refer to 006           017         0-1         Refer to 5.5           023         1-60(second)         The running time of aging test           024         1-60(second)         The idle time of aging test           025         1-720(hour)         The total time of aging test           036         0-2         Set to *1/2* active the aging test           031         0-1         Safety switch function           1 = open         0 = close           032         0-1         Polarity of safety switch           0 = Normal closed         1 = Normal opened           035         0 = 359         Angle of pull back after trimming           048         0 = 100         The duty of clamp SOL           051         0 = 1         Refer to 5.5           056         0 = 4095         Pedal input MAX value: value ≥ 057           057         0 = 4095         Pedal input Mix dividing value of high speed and low speed: 056 ≥ value ≥ O58           058         0 = 4095         Pedal input dividing value of Balance and Foot lifter: 058 ≥ value ≥ O60           060         0 = 4095         Pedal input dividing value of Balance and Foot lifter: 058 ≥ value ≥ O60           061         0 = 4095         Pedal input dividing value of Foot lifter and Trimmi			1 = Automatic foot lifter release after the time of O07				
007         S-30(second)         Refer to 006           017         0-1         Refer to 5.5           023         1-60(second)         The running time of aging test           024         1-60(second)         The idle time of aging test           025         1-720(hour)         The total time of aging test           036         0-2         Set to *1/2* active the aging test           031         0-1         Safety switch function           1 = open         0 = close           032         0-1         Polarity of safety switch           0 = Normal closed         1 = Normal opened           035         0 = 359         Angle of pull back after trimming           048         0 = 100         The duty of clamp SOL           051         0 = 1         Refer to 5.5           056         0 = 4095         Pedal input MAX value: value ≥ 057           057         0 = 4095         Pedal input Mix dividing value of high speed and low speed: 056 ≥ value ≥ O58           058         0 = 4095         Pedal input dividing value of Balance and Foot lifter: 058 ≥ value ≥ O60           060         0 = 4095         Pedal input dividing value of Balance and Foot lifter: 058 ≥ value ≥ O60           061         0 = 4095         Pedal input dividing value of Foot lifter and Trimmi			0 = always hold				
023         1~60(second)         The running time of aging test           024         1~60(second)         The idle time of aging test           025         1~720(hour)         The total time of aging test           026         0~2         Set to "1/2" active the aging test           031         0~1         Safety switch function 1 = open 0 = 0 = close           032         0~1         Polarity of safety switch 0 = Normal closed 1 = Normal opened           035         0~359         Angle of pull back after trimming           048         0~100         The duty of clamp SOL           051         0~1         Refer to 5.5           056         0~4095         Pedal input dividing value ≥ 057           057         0~4095         Pedal input dividing value of high speed and low speed: 056 ≥ value ≥ 058           058         0~4095         Pedal input dividing value of waspeed and Balance: 057 ≥ value ≥ 059           059         0~4095         Pedal input dividing value of Balance and Foot lifter: 058 ≥ value ≥ 060           060         0~4095         Pedal input dividing value of Balance and Foot lifter: 058 ≥ value ≥ 060           061         0~4095         Pedal input dividing value of Foot lifter and Trimming: 059 ≥ value ≥ 060           061         0~4095         Pedal input dividing value of Goot lifter and Value of the poly	O07	5~30(second)	Refer to O06				
024         1~60(second)         The idle time of aging test           025         1~720(hour)         The total time of aging test           026         0~2         Set to "1/2" active the aging test           031         0~1         Safety switch function	O17	0~1	Refer to 5.5				
O25         1~720(hour)         The total time of aging test           O26         0~2         Set to "1/2" active the aging test           O31         0~1         Safety switch function 1 = open 0 = close           O32         0~1         Polarity of safety switch 0 = Normal closed 1 = Normal opened           O35         0~359         Angle of pull back after trimming           O48         0~100         The duty of clamp SOL           O51         0~1         Refer to 5.5           O56         0~4095         Pedal input dividing value > O57           O57         0~4095         Pedal input dividing value of low speed and low speed: O56 ≥ value ≥ O58           O58         0~4095         Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59           O59         0~4095         Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60           O60         0~4095         Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61           O61         0~4095         Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61           O61         0~4095         Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61           O61         0~4095         Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O60           O63         0~5	O23	1~60(second)	The running time of aging test				
O26         0~2         Set to "1/2" active the aging test           O31         0~1         Safety switch function 1 = open 0 = close           O32         0~1         Polarity of safety switch 0 = Normal closed 1 = Normal opened           O35         0~359         Angle of pull back after trimming           O48         0~100         The duty of clamp SOL           O51         0~1         Refer to 5.5           O56         0~4095         Pedal input dividing value ≥ O57           O57         0~4095         Pedal input dividing value of high speed and low speed: O56 ≥ value ≥ O58           O58         0~4095         Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59           O59         0~4095         Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60           O60         0~4095         Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61           O61         0~4095         Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61           O61         0~4095         Pedal mode oli linear oli l	O24	1~60(second)					
O31       0~1       Safety switch function 1 = open 0 = close         O32       0~1       Polarity of safety switch 0 = Normal closed 1 = Normal opened         O35       0~359       Angle of pull back after trimming         O48       0~100       The duty of clamp SOL         O51       0~1       Refer to 5.5         O56       0~4095       Pedal input MAX value: value ≥ O57         O57       0~4095       Pedal input dividing value of high speed and low speed: O56 ≥ value ≥ O58         O58       0~4095       Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59         O59       0~4095       Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60         O60       0~4095       Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O60         O61       0~4095       Pedal input MIN value: value ≤ O60         O63       0~5       Pedal input MIN value: value ≤ O60         O63       0~5       Pedal input MIN value: value ≤ O60         O64       500~5000       The speed of turning point when O63 set as 1         The value of turning point when O63 set as 1       The value of turning point: O56 ≥ value ≥ O57         O69       0~1       Correction mode 0 = only the machine stopped 1 = before trimming         O83       0~720 <td>O25</td> <td>1~720(hour)</td> <td>The total time of aging test</td>	O25	1~720(hour)	The total time of aging test				
032       0~1       Polarity of safety switch         0 = Normal closed       1 = Normal opened         035       0~359       Angle of pull back after trimming         048       0~100       The duty of clamp SOL         051       0~1       Refer to 5.5         056       0~4095       Pedal input MAX value: value ≥ 057         057       0~4095       Pedal input dividing value of high speed and low speed: 056 ≥ value ≥ 058         058       0~4095       Pedal input dividing value of low speed and Balance: 057 ≥ value ≥ 059         059       0~4095       Pedal input dividing value of Balance and Foot lifter: 058 ≥ value ≥ 060         060       0~4095       Pedal input dividing value of Foot lifter and Trimming: 059 ≥ value ≥ 060         061       0~4095       Pedal input MIN value: value ≤ 060         063       0~5       Pedal mode 0 = linear 1 = polyline 2 = curve(slow → quick)         0 = curve(quick → slow)       3 = curve(quick → slow)         4 = S curve(quick → slow)       5 = S curve(quick → slow)         5 = S curve(quick → slow)       5 = S curve(quick → slow)         65       0~4095       The value of turning point when 063 set as 1         065       0~4095       The value of turning point: 056 ≥ value ≥ 057         069       0~1       Correction mode 0 = on	O26	0~2	Set to "1/2" active the aging test				
032       0~1       Polarity of safety switch         0 = Normal closed       1 = Normal opened         035       0~359       Angle of pull back after trimming         048       0~100       The duty of clamp SOL         051       0~1       Refer to 5.5         056       0~4095       Pedal input MAX value: value ≥ 057         057       0~4095       Pedal input dividing value of high speed and low speed: 056 ≥ value ≥ 058         058       0~4095       Pedal input dividing value of low speed and Balance: 057 ≥ value ≥ 059         059       0~4095       Pedal input dividing value of Balance and Foot lifter: 058 ≥ value ≥ 060         060       0~4095       Pedal input dividing value of Foot lifter and Trimming: 059 ≥ value ≥ 061         061       0~4095       Pedal input MIN value: value ≤ 060         063       0~5       Pedal mode 0 = linear 1 = polyline 2 = curve(slow → quick) 3 = curve(quick → slow); 4 = S curve(quick → slow); 4 = S curve(quick → slow) 5 = S curve(quick → slow) 7 = S cur	O31	0~1	Safety switch function				
032       0-1       Polarity of safety switch 0 = Normal closed 1 = Normal opened         035       0~359       Angle of pull back after trimming         048       0~100       The duty of clamp SOL         051       0~1       Refer to 5.5         056       0~4095       Pedal input MAX value: value ≥ O57         057       0~4095       Pedal input dividing value of high speed and low speed: 056 ≥ value ≥ O58         058       0~4095       Pedal input dividing value of low speed and Balance: 057 ≥ value ≥ O59         059       0~4095       Pedal input dividing value of Balance and Foot lifter: 058 ≥ value ≥ O60         060       0~4095       Pedal input dividing value of Foot lifter and Trimming: 059 ≥ value ≥ O61         061       0~4095       Pedal input MIN value: value ≤ O60         063       0~5       Pedal mode 0 = linear 1 = polyline 2 = curve(slow → quick) 3 = curve(quick → slow); 4 = S curve(quick → slow); 4 = S curve(quick → slow); 4 = S curve(quick → slow) → quick) 5 = S curve(quick → slow) → quick) 1 = S curve(quick → slow) + quick → slow → quick) 1 = S curve(quick → slow) + quick → slow) + quick → slow → quick → slo			1 = open				
0 = Normal closed         1 = Normal opened         035       0~359       Angle of pull back after trimming         048       0~100       The duty of clamp SOL         051       0~1       Refer to 5.5         056       0~4095       Pedal input MAX value: value ≥ O57         057       0~4095       Pedal input dividing value of high speed and low speed: O56 ≥ value ≥ O58         058       0~4095       Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59         059       0~4095       Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60         060       0~4095       Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61         061       0~4095       Pedal input MIN value: value ≤ O60         063       0~5       Pedal mode			0 = close				
035       0~359       Angle of pull back after trimming         048       0~100       The duty of clamp SOL         051       0~1       Refer to 5.5         056       0~4095       Pedal input MAX value: value ≥ O57         057       0~4095       Pedal input dividing value of high speed and low speed: O56 ≥ value ≥ O58         058       0~4095       Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59         059       0~4095       Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60         060       0~4095       Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61         061       0~4095       Pedal input MIN value: value ≤ O60         063       0~5       Pedal mode 0 = linear 1 = polyline 2 = curve(slow → quick) 3 = curve(quick → slow); 4 = S curve(quick → slow); 4 = S curve(quick → slow) → quick)         3 = curve(quick → slow) → quick)       3 = curve(quick → slow) → quick)         064       500~5000       The speed of turning point when O63 set as 1         065       0~4095       The value of turning point: O56 ≥ value ≥ O57         069       0~1       Correction mode 0 = only the machine stopped 1 = before trimming         083       0~720       Step width for electronic hand wheel	O32	0~1	Polarity of safety switch				
035         0~359         Angle of pull back after trimming           048         0~100         The duty of clamp SOL           051         0~1         Refer to 5.5           056         0~4095         Pedal input MAX value: value ≥ O57           057         0~4095         Pedal input dividing value of high speed and low speed: O56 ≥ value ≥ O58           058         0~4095         Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59           059         0~4095         Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60           060         0~4095         Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61           061         0~4095         Pedal mode O = linear OFF OFF OFF OFF OFF OFF OFF OFF OFF OF			0 = Normal closed				
048         0~100         The duty of clamp SOL           051         0~1         Refer to 5.5           056         0~4095         Pedal input MAX value: value ≥ O57           057         0~4095         Pedal input dividing value of high speed and low speed: O56 ≥ value ≥ O58           058         0~4095         Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59           059         0~4095         Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60           060         0~4095         Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61           061         0~4095         Pedal input MIN value: value ≤ O60           063         0~5         Pedal mode			1 = Normal opened				
O51         0~1         Refer to 5.5           O56         0~4095         Pedal input MAX value: value ≥ 057           O57         0~4095         Pedal input dividing value of high speed and low speed: O56 ≥ value ≥ O58           O58         0~4095         Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59           O59         0~4095         Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60           O60         0~4095         Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61           O61         0~4095         Pedal mode Oelinear           0 = linear         1 = polyline           2 = curve(slow → quick)         3 = curve(quick → slow);           4 = S curve(quick → slow)         5 = S curve(quick → slow)           5 = S curve(quick → slow → quick)           3 = curve(quick → slow)         5 = S curve(quick → slow)           65         0~4095         The value of turning point when O63 set as 1           O65         0~4095         The value of turning point: O56 ≥ value ≥ O57           O69         0~1         Correction mode O = only the machine stopped O = only the	O35	0~359	Angle of pull back after trimming				
O56         0~4095         Pedal input MAX value: value ≥ O57           O57         0~4095         Pedal input dividing value of high speed and low speed: O56 ≥ value ≥ O58           O58         0~4095         Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59           O59         0~4095         Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60           O60         0~4095         Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61           O61         0~4095         Pedal input MIN value: value ≤ O60           O63         0~5         Pedal mode 0 = linear 1 = polyline 2 = curve(slow → quick) 3 = curve(quick → slow); 4 = S curve(quick → slow); 4 = S curve(quick → slow) 5 = S curve(quick → slow) 4 = S curve(quick → slow) 5 = S curve(quick → slow → quick)           O64         500~5000         The speed of turning point when O63 set as 1           O65         0~4095         The value of turning point when O63 set as 1           O69         0~1         Correction mode 0 = only the machine stopped 1 = before trimming           O83         0~720         Step width for electronic hand wheel           O84         0~200         Speed for electronic hand wheel	O48	0~100	The duty of clamp SOL				
O57       0~4095       Pedal input dividing value of high speed and low speed: O56 ≥ value ≥ O58         O58       0~4095       Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59         O59       0~4095       Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60         O60       0~4095       Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61         O61       0~4095       Pedal input MIN value: value ≤ O60         O63       0~5       Pedal mode 0 = linear 1 = polyline 2 = curve(slow → quick) 3 = curve(quick → slow); 4 = S curve(quick → slow); 4 = S curve(quick → slow) 5 = S curve(quick → slow) 5 = S curve(quick → slow) 4 = S curve(quick → slow) 5 = S curve(quick → slow) 5 = S curve(quick → slow) 6 = S curve(quick → slow) 6 = S curve(quick → slow) 6 = S curve(quick → slow) 7 = S curve(quick →	O51	0~1	Refer to 5.5				
O58       0~4095       Pedal input dividing value of low speed and Balance: O57 ≥ value ≥ O59         O59       0~4095       Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60         O60       0~4095       Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61         O61       0~4095       Pedal input MIN value: value ≤ O60         O63       0~5       Pedal mode 0 = linear 1 = polyline 2 = curve(slow → quick) 3 = curve(quick → slow); 4 = S curve(quick → slow); 4 = S curve(quick → slow) 5 = S curve(quick → slow) 4 = S curve(quick → slow) 5 = S curve(quick → slow) 5 = S curve(quick → slow) 6 = S curve(quick → slow) 7 = S curve(	O56	0~4095	Pedal input MAX value: value ≥ O57				
O58       0~4095       Pedal input dividing value of low speed and Balance: $O57 \ge value \ge O59$ O59       0~4095       Pedal input dividing value of Balance and Foot lifter: $O58 \ge value \ge O60$ O60       0~4095       Pedal input dividing value of Foot lifter and Trimming: $O59 \ge value \ge O61$ O61       0~4095       Pedal input MIN value: value ≤ O60         O63       0~5       Pedal mode $0 = linear$ $1 = polyline$ $2 = curve(slow → quick)$ $3 = curve(quick → slow);$ $4 = S curve(quick → slow);$ $4 = S curve(quick → slow) → quick)$ O64       500~5000       The speed of turning point when O63 set as 1         O65       0~4095       The value of turning point: O56 ≥ value ≥ O57         O69       0~1       Correction mode $0 = only$ the machine stopped $0 = only$ step width for electronic hand wheel         O83       0~720       Step width for electronic hand wheel	O57	0~4095	Pedal input dividing value of high speed and low				
O59       0~4095       Pedal input dividing value of Balance and Foot lifter:			speed: O56 ≥ value ≥ O58				
O59       0~4095       Pedal input dividing value of Balance and Foot lifter: O58 ≥ value ≥ O60         O60       0~4095       Pedal input dividing value of Foot lifter and Trimming: O59 ≥ value ≥ O61         O61       0~4095       Pedal input MIN value: value ≤ O60         O63       0~5       Pedal mode 0 = linear 1 = polyline 2 = curve(slow → quick) 3 = curve(quick → slow); 4 = S curve(gloick → slow) → quick) 5 = S curve(quick → slow → quick)         O64       500~5000       The speed of turning point when O63 set as 1         O65       0~4095       The value of turning point: O56 ≥ value ≥ O57         O69       0~1       Correction mode 0 = only the machine stopped 1 = before trimming         O83       0~720       Step width for electronic hand wheel         O84       0~200       Speed for electronic hand wheel	O58	0~4095	Pedal input dividing value of low speed and Balance:				
O58 ≥ value ≥ O60         O60       0~4095       Pedal input dividing value of Foot lifter and Trimming:         O59 ≥ value ≥ O61       O61       0~4095       Pedal input MIN value: value ≤ O60         O63       0~5       Pedal mode         0 = linear       1 = polyline         2 = curve(slow → quick)       3 = curve(quick → slow);         4 = S curve(glow → quick)       4 = S curve(quick → slow)         5 = S curve(quick → slow) → quick)       5 = S curve(quick → slow)         064       500~5000       The speed of turning point when O63 set as 1         O65       0~4095       The value of turning point: O56 ≥ value ≥ O57         O69       0~1       Correction mode         0 = only the machine stopped       1 = before trimming         O83       0~720       Step width for electronic hand wheel         O84       0~200       Speed for electronic hand wheel			O57 ≥ value ≥ O59				
O60 $0\sim4095$ Pedal input dividing value of Foot lifter and Trimming: $O59 \ge value \ge O61$ O61 $0\sim4095$ Pedal input MIN value: value ≤ O60O63 $0\sim5$ Pedal mode $0=linear$ $1=polyline$ $2=curve(slow → quick)$ $3=curve(quick → slow);$ $4=S$ curve(slow → quick → slow) $5=S$ curve(quick → slow → quick)O64 $500\sim5000$ The speed of turning point when O63 set as 1O65 $0\sim4095$ The value of turning point: $O56 \ge value \ge O57$ O69 $0\sim1$ Correction mode $0=only$ the machine stopped $1=before$ trimmingO83 $0\sim720$ Step width for electronic hand wheelO84 $0\sim200$ Speed for electronic hand wheel	O59	0~4095	Pedal input dividing value of Balance and Foot lifter:				
O59 ≥ value ≥ O61  O61			O58 ≥ value ≥ O60				
O61 $0\sim4095$ Pedal input MIN value: value ≤ O60         O63 $0\sim5$ Pedal mode $0 = linear$ $1 = polyline$ $2 = curve(slow → quick)$ $3 = curve(quick → slow);$ $4 = S curve(quick → slow) + quick)$ $5 = S curve(quick → slow → quick)$ O64 $500\sim5000$ The speed of turning point when O63 set as 1         O65 $0\sim4095$ The value of turning point: $0.56 \ge value \ge 0.57$ O69 $0\sim1$ Correction mode $0 = 0.00$ only the machine stopped $0 = 0.00$ only the machine stopped $0 = 0.00$ only the machine stopped $0.00$ only the machine stopped	O60	0~4095	Pedal input dividing value of Foot lifter and Trimming:				
O63       0~5       Pedal mode         0 = linear       1 = polyline         2 = curve(slow → quick)       3 = curve(quick → slow);         4 = S curve(slow → quick → slow)       5 = S curve(quick → slow → quick)         O64       500~5000       The speed of turning point when O63 set as 1         O65       0~4095       The value of turning point: O56 ≥ value ≥ O57         O69       0~1       Correction mode         0 = only the machine stopped       1 = before trimming         O83       0~720       Step width for electronic hand wheel         O84       0~200       Speed for electronic hand wheel			O59 ≥ value ≥ O61				
$0 = linear$ $1 = polyline$ $2 = curve(slow \rightarrow quick)$ $3 = curve(quick \rightarrow slow);$ $4 = S curve(slow \rightarrow quick \rightarrow slow)$ $5 = S curve(quick \rightarrow slow \rightarrow quick)$ $064                                    $	O61	0~4095	Pedal input MIN value: value ≤ O60				
$1 = polyline$ $2 = curve(slow \rightarrow quick)$ $3 = curve(quick \rightarrow slow);$ $4 = S curve(slow \rightarrow quick \rightarrow slow)$ $5 = S curve(quick \rightarrow slow \rightarrow quick)$ $064                                    $	O63	0~5	Pedal mode				
$2 = \text{curve}(\text{slow} \rightarrow \text{quick})$ $3 = \text{curve}(\text{quick} \rightarrow \text{slow});$ $4 = S \text{ curve}(\text{slow} \rightarrow \text{quick}) \rightarrow \text{slow}$ $5 = S \text{ curve}(\text{quick} \rightarrow \text{slow} \rightarrow \text{quick})$ $064 \qquad 500 \sim 5000 \qquad \text{The speed of turning point when 063 set as 1}$ $065 \qquad 0 \sim 4095 \qquad \text{The value of turning point: 056} \geq \text{value} \geq \text{057}$ $069 \qquad 0 \sim 1 \qquad \text{Correction mode}$ $0 = \text{only the machine stopped}$ $1 = \text{before trimming}$ $083 \qquad 0 \sim 720 \qquad \text{Step width for electronic hand wheel}$ $084 \qquad 0 \sim 200 \qquad \text{Speed for electronic hand wheel}$			0 = linear				
$3 = \text{curve}(\text{quick} \rightarrow \text{slow});$ $4 = S \text{ curve}(\text{slow} \rightarrow \text{quick} \rightarrow \text{slow})$ $5 = S \text{ curve}(\text{quick} \rightarrow \text{slow} \rightarrow \text{quick})$ $064 \qquad 500 \sim 5000 \qquad \text{The speed of turning point when O63 set as 1}$ $065 \qquad 0 \sim 4095 \qquad \text{The value of turning point: O56} \geq \text{value} \geq \text{O57}$ $069 \qquad 0 \sim 1 \qquad \text{Correction mode}$ $0 = \text{only the machine stopped}$ $1 = \text{before trimming}$ $083 \qquad 0 \sim 720 \qquad \text{Step width for electronic hand wheel}$ $084 \qquad 0 \sim 200 \qquad \text{Speed for electronic hand wheel}$			1 = polyline				
$4 = S \text{ curve}(\text{slow} \rightarrow \text{quick} \rightarrow \text{slow})$ $5 = S \text{ curve}(\text{quick} \rightarrow \text{slow} \rightarrow \text{quick})$ $064 \qquad 500 \sim 5000 \qquad \text{The speed of turning point when 063 set as 1}$ $065 \qquad 0 \sim 4095 \qquad \text{The value of turning point: } 056 \geq \text{value} \geq 057$ $069 \qquad 0 \sim 1 \qquad \text{Correction mode}$ $0 = \text{only the machine stopped}$ $1 = \text{before trimming}$ $083 \qquad 0 \sim 720 \qquad \text{Step width for electronic hand wheel}$ $084 \qquad 0 \sim 200 \qquad \text{Speed for electronic hand wheel}$			$2 = \text{curve(slow} \rightarrow \text{quick)}$				
5 = S curve(quick → slow → quick)  The speed of turning point when O63 set as 1  O65 0~4095 The value of turning point: O56 ≥ value ≥ O57  O69 0~1 Correction mode 0 = only the machine stopped 1 = before trimming  O83 0~720 Step width for electronic hand wheel  O84 0~200 Speed for electronic hand wheel			$3 = \text{curve}(\text{quick} \rightarrow \text{slow});$				
O64       500~5000       The speed of turning point when O63 set as 1         O65       0~4095       The value of turning point: O56 ≥ value ≥ O57         O69       0~1       Correction mode 0 = only the machine stopped 1 = before trimming         O83       0~720       Step width for electronic hand wheel         O84       0~200       Speed for electronic hand wheel			$4 = S \text{ curve}(\text{slow } \rightarrow \text{ quick } \rightarrow \text{ slow})$				
O65 $0\sim4095$ The value of turning point: $O56 \ge value \ge O57$ O69 $0\sim1$ Correction mode $0 = only$ the machine stopped $1 = before trimming$ O83 $0\sim720$ Step width for electronic hand wheelO84 $0\sim200$ Speed for electronic hand wheel			$5 = S \text{ curve}(\text{quick} \rightarrow \text{slow} \rightarrow \text{quick})$				
O69 $0\sim1$ Correction mode $0 = \text{only the machine stopped}$ $1 = \text{before trimming}$ O83 $0\sim720$ Step width for electronic hand wheelO84 $0\sim200$ Speed for electronic hand wheel	O64	500~5000	The speed of turning point when O63 set as 1				
$0 = \text{only the machine stopped}$ $1 = \text{before trimming}$ $083 \qquad 0 \sim 720 \qquad \text{Step width for electronic hand wheel}$ $084 \qquad 0 \sim 200 \qquad \text{Speed for electronic hand wheel}$	O65	0~4095					
1 = before trimming O83 0~720 Step width for electronic hand wheel O84 0~200 Speed for electronic hand wheel	O69	0~1					
O830~720Step width for electronic hand wheelO840~200Speed for electronic hand wheel							
O84 0~200 Speed for electronic hand wheel			1 = before trimming				
· ·	O83	0~720	Step width for electronic hand wheel				
O91 1~10 Stitches of start with 2 nd stitch length	O84	0~200					
	O91	1~10	Stitches of start with 2 nd stitch length				

# 10. ERROE MESSAGES & POSSIBLE TROUBLESHOOTING

ERROE	DESCRIPTION	SOLUTION				
CODE						
		- Check or replace the pedal				
PEDAL	Pedal warning	- Pedal not connected				
		- Do not pedal yet				
CARE	Safe Switch problem	- Check the Safe Switch				
CAIL	Sale Switch problem	- Replace the safe switch				
KEY1	Machine button	- Do not press machine button				
KLII	warning	- Replace the buttons				
		- Check mains voltage				
E101	High AC voltage fault	- Stabilize mains voltage				
		- Use generator				
		- Check mains voltage				
E103	High Bus voltage fault	- Stabilize mains voltage				
		- Use generator				
	Bus current overload	- Check the encoder and motor				
E106		- Replace the encoder				
		- Replace the motor				
	Motor blocked	- Eliminate stiff movement in the				
F107		machine				
E107		- Replace the encoder				
		- Replace the motor				
		- check or replace the synchronizer for a				
F110	Encoder/Synchronizer	belt-drive machine				
E110	fault	- check or replace the encoder for a				
		direct-drive machine				
	Software Update	- Software update				
E190, E290	Error	- Replace the control				
E191,	Software Update	- Software update				
E291	Error	- Replace the control				
E193,	Software Update	- Software update				
E293	Error	- Replace the control				
F204	Software Update	- Software update				
E294	Communication Error	- Replace the control				
F100	Software Update	- Software update				
E199	Error	- Replace the control				
F000	Communication	- Restart the control				
E900	problem	- Replace the control				

# 11. Controller Check

Press hold S during power on, it will display "TEST" and then enter the Check interface. Seven-Segment diplay A display check index, the else display contents.

#### 11.1Pedal

Display B,C shows the pedal position status, display D,E,F,G display sample value.

ЬL	Balance position	
L5	Low-speed position, is stepping on the first paragraph	
H'5	High-speed position, is stepping on the second paragraph	
FP	Foot position, anti-step on the first paragraph	
ГΠ	Trim position, anti-step on the second paragraph	
Er	Not connected or the pedal is faulty	

#### 11.2Synchronizer

Synchronizer: turning the motor, display C value changes from 0 to 1 Position encoder: turning the motor, display D E,F,G value changes between 0 to 720.

#### 11.3Keypad Test

Display B, C, D, E, F, G correspond to the six keys on keypad, when press the key, the corresponding display will change from 0 to 1, press to light on the corresponding LED, press to light off, to light on all and to

light off all, the correspondence between the digital tube and the function key

is as follows
Display B: foot stroke

Display C: start and end trips Display D: position of the needle

Display E: stitch length

Display F: additional thread tension

Display G: pause

### 11.4Motor encoder

#### 11.5Output Device

Digital F, G shows the current test solenoid type, the corresponding relationship is as follows

Solenoid	Display
Trimmer	1
Foot	Fo
Reverse	r-E
Stroke	7-1-
Stitch length	<u> </u>
Clamp	ΕL
Main thread tension	חר
Additional thread tension	8Ľ
Seam middle guide	NJ

Press S to test.

#### 11.6Input Switches

Display C: status of Reverse switch

Display E: status of Safety Switch

Display G: status of Knee Stroke Switch

#### 11.7 Electronic Handwheel

Display B: Rotation
Display C: Press Switch
Display DEFG: Encoder

#### 11.8Speed Limit Device to stroke

Digital Type: four gears

 Display C shows gear, display E, G display the status of the two switches inside.

Analog Type: Stepless speed change

- DisplayD, E, F, G show the sample value of the potentiometer.
- Adjustment: press [P] to save two gear position, and press [S] to save six gear position.

#### 11.9AC voltage

Display the current AC input voltage

e.g: 🖯 💆 💆 AC voltage 220v.

# 11.10 Bus voltage

Display the current bus input voltage

e.g:  $\beta = \beta / |\Omega|$ , bus voltage 310v.

- 11.11 A phase current sampling reference
- 11.12 B phase current sampling reference
- 11.13 AD1 sample value
- 11.14 AD2 sample value
- 11.15 AD3 sample value
- 11.16 AD4 sample value
- 11.17 Main MCU Software Version

E.g. H No IDD, version1.00

#### 11.18 Software Release Date

E.g. 15 100 1, released on October 1, 2016

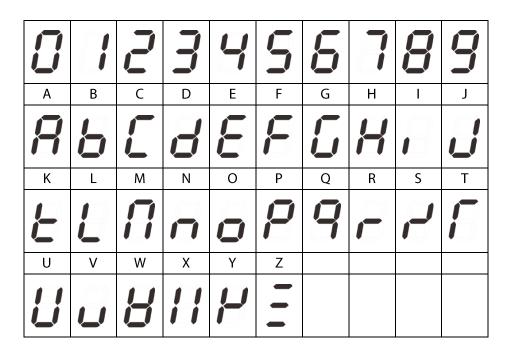
#### 11.19 Slave MCU Software Version

E.g: レ トロ !ロロ,version1.00

# 12. Appendix

# 12.1 Seven-Segment Display Characters Compare Table

0 1 2 3	4	5	6	7	8	9
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# 12.2How to update the control box with the update module

User can update software of the control box by update module if necessary, the operations showed as below

- Switch off the power, plug the update module into speed controller
- Switch on the power, upgrading starts automatically, it will be accomplished after "ALL OK" displayed. Then switch off and plug the speed controller, all function will be normal after switch on again.